

## AM Stereo Radio

### Description

The CXA1017M is an IC for use with AM stereo radio, with an AM stereo system identification and audio signal processing functions integrated.

### Features

- It identifies all AM stereo broadcasting systems (Mugnvox, Kahn, Motorola and Harris) and switching the reception mode automatically.
- By employing a PLL (Phase Locked Loop) pilot detection circuit and safety logic circuit, single channel interference or malfunction due to I.P.M. (Incidental Phase Modulation) is eliminated.
- System identification time is minimized to about one second.
- Single adjustment (using a semi-fixed resistor for VCO).
- Few peripheral parts required.
- High S/N ratio and low distortion factor.

### Functions

- PLL pilot detection circuit
- PSN (90° Phase Shift Network)
- Matrix circuit
- Malfunction preventive circuit
- Mute control output
- LED driver

### Structure

Bipolar silicon monolithic IC

### Absolute Maximum Ratings (Ta = 25°C)

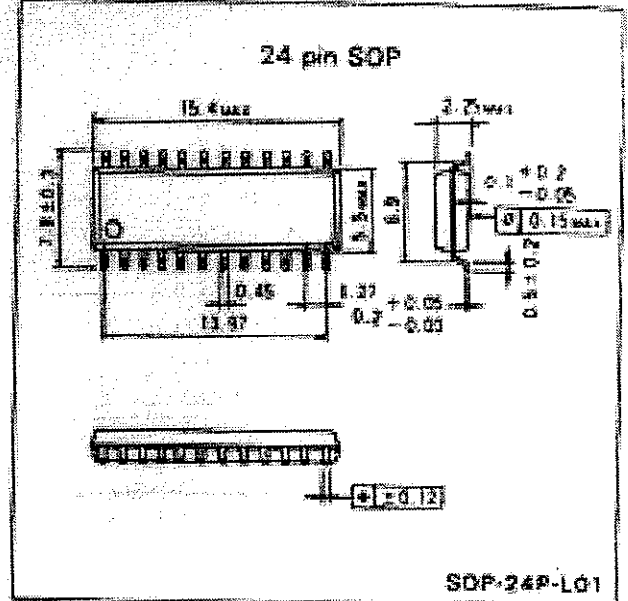
• Supply voltage	Vcc	9	V
• Operating temperature	Topr	-20 to +75	°C
• Storage temperature	Tstg	-55 to +150	°C
• Allowable power dissipation	Pd	524	mW

### Recommended Operating Condition

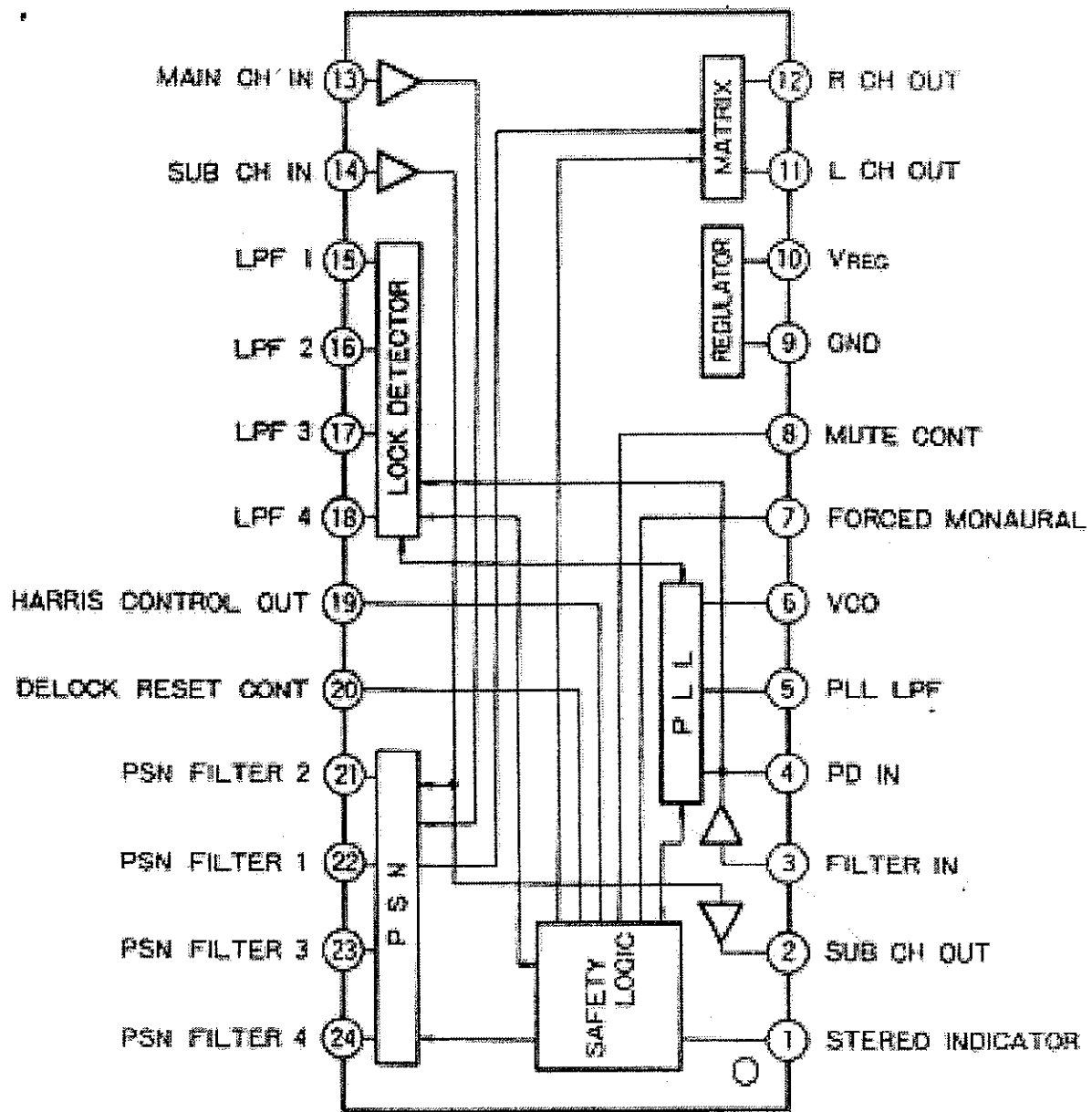
• Supply voltage	Vcc	5 to 8.5	V
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### Package Outline

Unit: mm



Block Diagram and Pin Configuration (Top View)



Pin Description

No.	Symbol	Equivalent circuit	Voltage (V) (Typ.)	Description
1	STEREO INDICATOR		8.0	LED drive circuit
2	SUB CH OUT		1.5	Buffer (0dB) output from Pin 18 (Sub ch IN)
14	SUB CH IN		1.5	L-R + pilot signal input circuit
3	FILTER IN		1.5	For pilot detection OP amplifier input for LPF
4	PD IN		1.5	OP amplifier output for LPF
5	PLL LPF		2.7	LPF for multi-PLL

No.	Symbol	Equivalent circuit	Voltage (V) (Typ.)	Description
6	VCO		2.8	For time constant of VCO for FLL
7	FORCED MONAURAL		0	Forced monaural reception with Hi-level pin input
20	LOCK OFF RESET CONT		0	Forced monaural reception with Low-level pin input
8	MUTE CONT		0	About $\pm 18$ ms 3.3 V pulse is generated mainly the moment matrix and PSN circuits are switched on or off.
9	GND		GND	
10	VREG		4.0	4V (typ.) of a regulator output is obtained from Vcc via RREG
11	Lch OUT		1.5	Lch signal output
12	Rch OUT		1.5	Rch signal output

No.	Symbol	Equivalent circuit	Voltage (V) (Typ.)	Description
13	MAIN CH IN		1.5	L + R signal input circuit
15	LPF 1		3.0	LPF for Harris detection comparator
16	LPF 2		3.0	LPF for Motorola detection comparator
17	LPF 3		3.0	LPF for Kahn detection comparator
18	LPF 4		3.0	LPF for Magnavox detection comparator
18	HARRIS CONT		2.2	Current is drawn for Harris reception
21	PSN FILTER 2		1.5	Capacitor for PSN filter is connected (1000PF)
22	PSN FILTER 1		1.5	Capacitor for PSN filter is connected (10000PF)
23	PSN FILTER 3		1.5	Capacitor for PSN filter is connected (10000PF)
24	PSN FILTER 4		1.5	Capacitor for PSN filter is connected (1000PF)

Electrical Characteristics (Ta = 25°C)

\* Input systems: MOT: Motorola; MAQ: Magnavox; HAH: Harris; EAH: Kahn  
(Vcc = 8V unless otherwise specified)

No.	Item	System*	Function (Symbol)								Test	Min.	Typ.	Max.	Unit
			1	2	A	3	4	5	6	7					
1	Vcc(1) Voltage RL	M1*		X	H	L	H	H	L	H	Measure with 8V at Vcc during no signal	1.5	2.0	4.5	V
2	Vcc(2) Voltage RL	M1*		H							Measure with 8V at Vcc during no signal	1.5	1.5	1.5	V
3	Vcc(3) Voltage RL	M1*		L							Measure with 8V at Vcc during no signal	1.5	1.0	1.5	V
4	OFF CHECK1 (OT1)	M1*										0.4	0.11	0.1	V
5	OFF CHECK1 (O2B)	M1*										0.4	1.0	2.1	V
6	OFF CHECK1 (MUTE)	M1*										0.1	0	0.1	V
7	Carrier VCO operation	M1*									Measure with Vcc at 2.0V to 2.5V no changing Vcc with Vcc = 2.5V, Vcc = 2.0V, Vcc = 2.5V	50.00 62.00		12.00 11.00	kHz
8	VCO synchronization	M1*									Measure by connecting V1 DC to 0V and V2 DC to 0V	0.5	0.7	0.9	V
9	BT AND CHECK	M1*	MOT								Input = 1.0Vrms pilot signal @ 2.0Vrms (1000) measuring point DC resistance less than 100Ω	0		0.0	V
10	BTN output level (B)	M1*	MOT		X						Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0	2.0	1.7	dBm
11	BTN output level (L)	M1*	MOT								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0	2.0	1.7	dBm
12	BTN operation (B)	M1*	MOT								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0			dB
13	BTN operation (L)	M1*	MOT								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0			dB
14	BTN operation factor (B)	M1*	MOT								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal			1.1	%
15	BTN operation factor (L)	M1*	MOT								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal			1.1	%
16	F-AMCND operation 1 (MOT)	M1*	MOT	ON		H						7.0	8.0	8.3	V
17	F-AMCND operation 2 (MOT)	M1*	MOT	L								7.0	8.0	8.3	V
18	MUTE1 pulse check 1	M1*	MOT								Check if MUTE output pulse more than 3V	0		11	rms
19	MUTE1 pulse check 2	M1*	MOT								Check if MUTE output pulse more than 3V	10		50	rms
20	SLACK H operation 1	M1*	MOT								Check if MUTE operation 1 by making C1 in 3V	7.0	8.0	8.1	V
21	SLACK H operation 2	M1*	MOT								Check if MUTE operation 2 by making C1 in 3V	7.0	8.0	8.1	V
22	MUTE1 pulse check 3	M1*	MOT								Check if MUTE output pulse more than 3V	0		11	rms
23	BT AND CHECK	M1*	MAQ								Input = 1.0Vrms if no BTDC pilot signal and V2 DC to 0V	0		0.0	V
24	BTN output level (B)	M1*	MAQ		X						Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0	2.0	1.7	dBm
25	BTN output level (L)	M1*	MAQ								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0	2.0	1.7	dBm
26	BTN operation (B)	M1*	MAQ								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0			dB
27	BTN operation (L)	M1*	MAQ								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal	2.0			dB
28	BTN operation factor (B)	M1*	MAQ								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal			1.1	%
29	BTN operation factor (L)	M1*	MAQ								Peak-to-peak output = 2.0Vrms if no BTDC signal in input simultaneously with pilot signal			1.1	%
30	F-AMCND operation 1 (MAQ)	M1*	MAQ	ON		H						7.0	8.0	8.1	V
31	F-AMCND operation 2 (MAQ)	M1*	MAQ	L								7.0	8.0	8.1	V

Electrical Characteristics (Ta = 25°C)

\* Input systems: MDT: Motorola MAG: Magnavox HAH: Harris KAH: Kahn  
 [Vcc = 5V unless otherwise specified]

No.	Item	Symbol	Characteristic	Input system										Test	Min.	Typ.	Max.	Unit
				1	2	3	4	5	6	7	8	9	10					
22	WRITE pulse check 1	M14	MAG		C	H	A	A	A	A	A	A	A	Check if MR becomes pulse more than 2V	-		11	ms
23	WRITE pulse check 2	M15	MAG											Check if MR becomes pulse more than 2V	14		25	ms
24	Load-R impedance 1 (BASE)	M12	MAG											Check if MR becomes H by loading C1 2V	7.4	8.0	8.3	V
25	Load-R impedance 2 (BASE)	M15	MAG											Check if MR becomes H by loading C1 2V	7.4	8.0	8.3	V
26	WRITE pulse check 3	M18	MAG											Three before pulse more than 2V in output after C1 is set to 2V	0		10	ms
27	READ output level (H)	M11				A								Low output voltage - 2.0V (if = 1.0V) signal is input	24	26	27	dBm
28	READ output level (L)	M10												High output voltage - 2.0V (if = 1.0V) signal is input	29	34	34	dBm
29	READ distortion factor (H)	M13												Low distortion factor voltage - 2.0V (if = 1.0V) signal is input			1.1	%
30	READ distortion factor (L)	M12												Low distortion factor voltage - 2.0V (if = 1.0V) signal is input			1.1	%
41	RT AND CHECK	M4	HAH							A		A		Input - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	0		0.8	V
42	READ output level (H)	M14	HAH											Input - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	0		0.8	V
43	READ output level (L)	M13	HAH			A								Low output voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	-23	-26	-27	dBm
44	READ output level (H)	M12	HAH											Low output voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	-24	-29	-27	dBm
45	READ distortion factor (H)	M11	HAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	23			dB
46	READ distortion factor (L)	M10	HAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	23			dB
47	READ distortion factor (H)	M13	HAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V			1.1	%
48	READ distortion factor (L)	M12	HAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V			1.1	%
49	WRITE impedance 1 (BASE)	M14	HAH			B		H						Check if MR becomes H when 2V is set to 2V	7.4	8.0	8.3	V
50	WRITE impedance 2 (BASE)	M15	HAH											Check if MR becomes H when 2V is set to 2V	7.4	8.0	8.3	V
51	WRITE pulse check 1	M17	HAH											Three before pulse more than 2V in output after C1 is set to 2V	0		10	ms
52	WRITE pulse check 2	M18	HAH											Three before pulse more than 2V in output after C1 is set to 2V	0		25	ms
53	Load-R impedance 1 (BASE)	M12	HAH											Check if MR becomes H by loading C1 2V	7.4	8.0	8.3	V
54	Load-R impedance 2 (BASE)	M15	HAH											Check if MR becomes H by loading C1 2V	7.4	8.0	8.3	V
55	WRITE pulse check 3	M18	HAH											Three before pulse more than 2V in output after C1 is set to 2V	0		11	ms
56	RT AND CHECK	M5	KAH											Input - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	0		0.8	V
57	READ output level (H)	M11	KAH			A		B						Low output voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	-23	26	27	dBm
58	READ output level (L)	M10	KAH											Low output voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V	-23	24	27	dBm
59	READ distortion factor (H)	M13	KAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V				dB
60	READ distortion factor (L)	M12	KAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V				dB
61	READ distortion factor (H)	M11	KAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V			1.1	%
62	READ distortion factor (L)	M10	KAH											Low distortion factor voltage - 2.0V (if = 1.0V) signal is input and outputting pulse 2V (base) from 0.5V			1.1	%

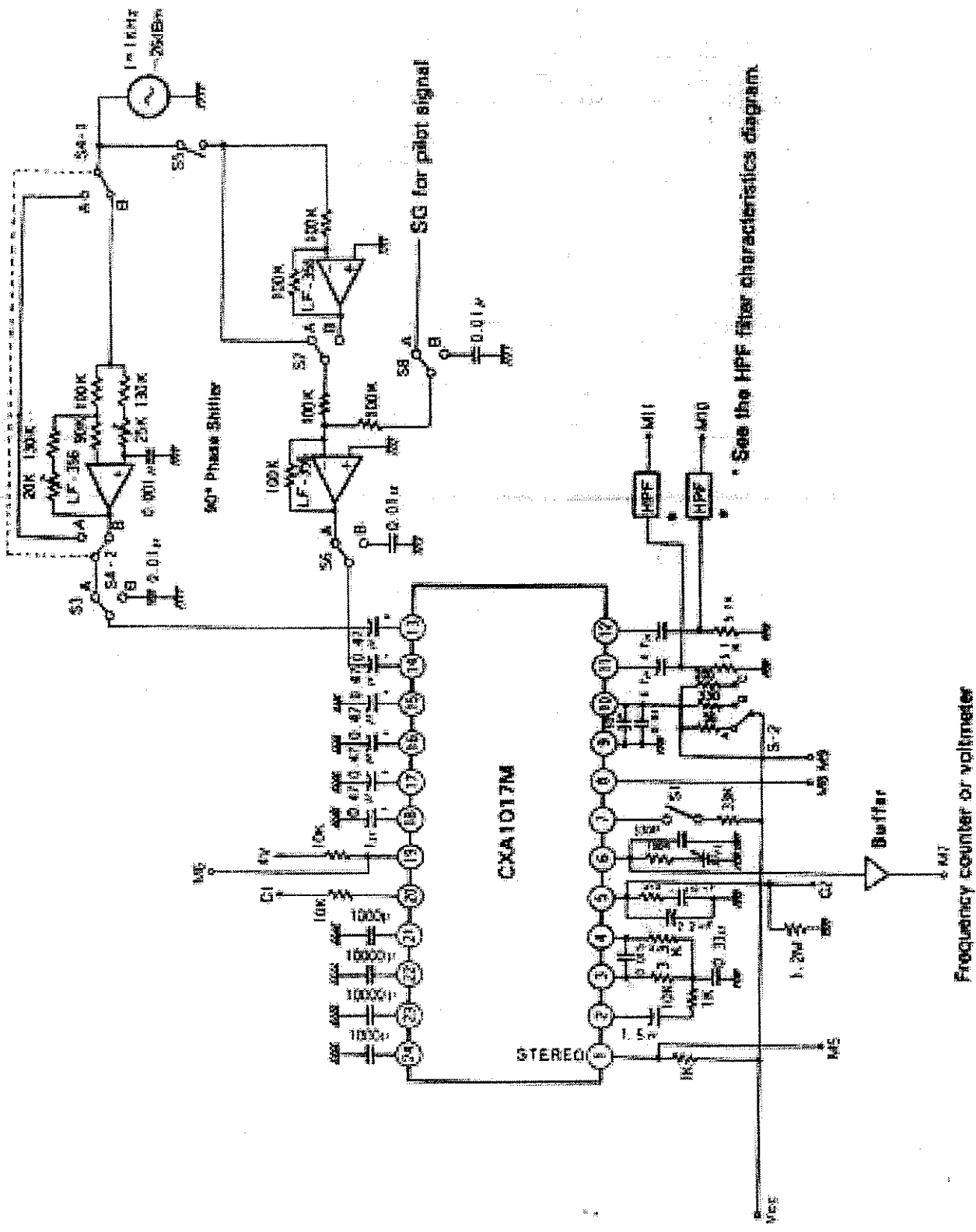
\* Input systems: MDT: Motorola HAR: Harris  
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 (Vcc = 5V unless otherwise specified)

Electrical Characteristics (Ta = 25°C)

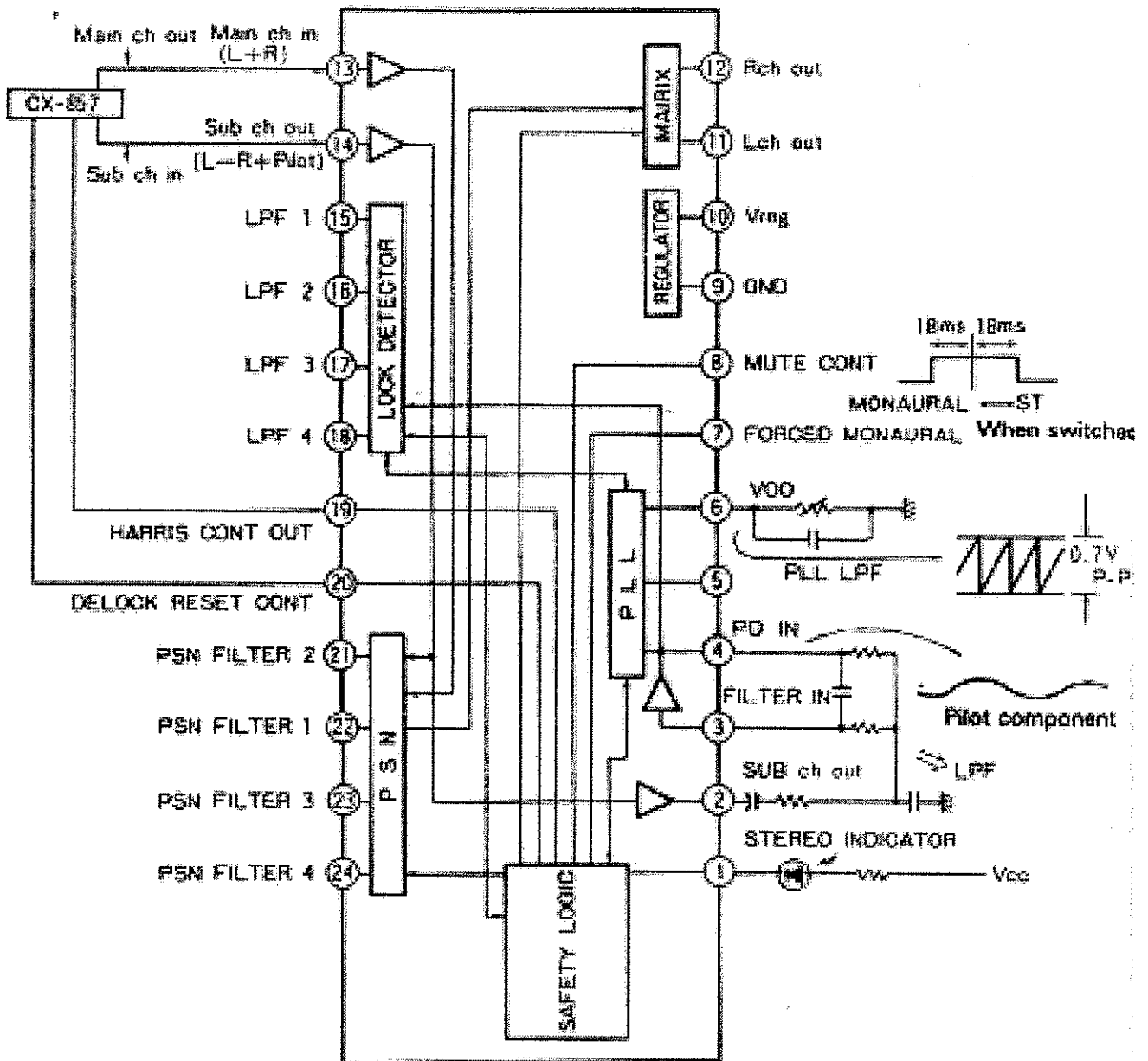
No.	Item	Symbol	Input system	Switch conditions Make ON for test number												Test	Min.	Typ.	Max.	Unit					
				1	2	3	4	5	6	7	8	9	10	11	12										
63	LOCK-# operation 1 K.A.H.	M1	KAH																		Check if MI becomes H when S1 is set to ON	7.5	8.0	8.1	V
64	LOCK-# operation 2 K.A.H.	M5	KAH																		Check if MI becomes H when S1 is set to ON	7.5	8.0	8.1	V
65	MUTE pulse check 1	M8	KAH																		Time before pulse more than DC = 2V is output when S1 is set to ON	0		11	ms
66	MUTE pulse check 2	M8	KAH																		Time before pulse more than DC = 3V is output when S1 is set to OFF	10		55	ms
67	LOCK-# operation 1 K.A.H.	M1	KAH																		Check if MI becomes H when C1 is set to 2V	7.5	8.0	8.1	V
68	LOCK-# operation 2 K.A.H.	M5	KAH																		Check if MI becomes H when C1 is set to 2V	7.5	8.0	8.1	V
69	MUTE pulse check 3	M8	KAH																		Time before pulse more than DC = 2V is output right after C1 is set to 2V	0		11	ms



Electrical Characteristics Test Circuit

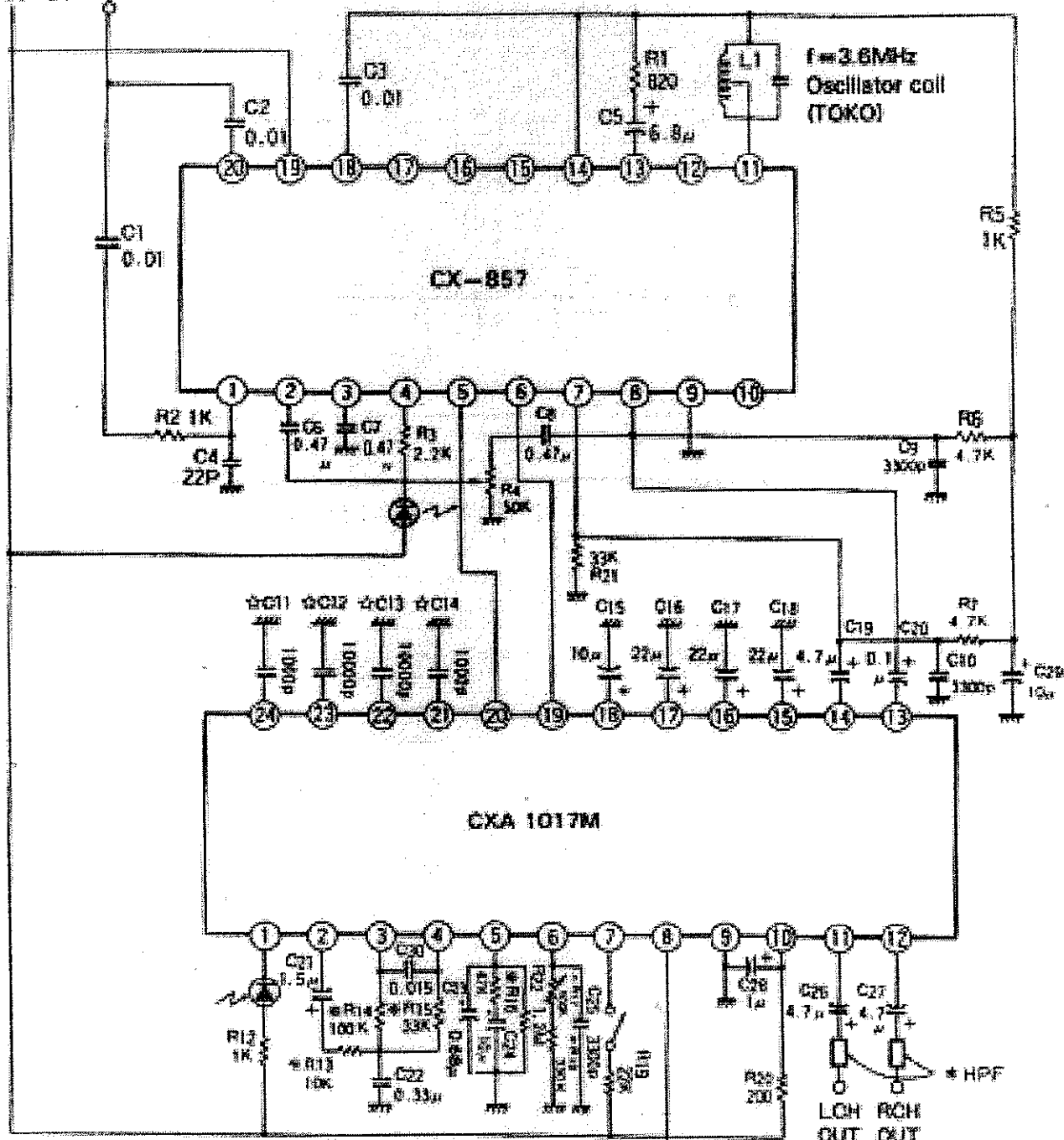


Application Circuit (1)



**Application Circuit (2)**

V<sub>cc</sub>=8V IF IN 450KHz 100mVrms



\* Metal film resistor  
 ☆ Mylar capacitor ±1%  
 C22 metal film capacitor  
 C25, C30 Mylar capacitors

\* See the HPF filter characteristics